Operating System

Lecture 12: Input/Output

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Today

- I/O Layering
- I/O Devices
- Device Drivers
- Device Controllers
- I/O Software

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I/O Layering

- I/O Layers
 - User processes
 - Device-independent software
 - Device drivers
 - Device Controllers
 - Devices (HW)



I/O Devices

- A computer system is composed of components
 - CPU, memory, I/O devices
 - Communication is over system bus
 - can be more than one

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Device Controllers

- An I/O device is made up of
 - mechanical components (if any)
 - electronic components
 - adapter or controller
- OS interacts with the controller using registers
- Registers accessed via memory (memory-mapped) or I/O instructions

Device Drivers

- Encapsulates device-dependent code
- Generally, must implement a standard interface
- Code contains device-specific register for reads/writes

Device-Independent OS Software

- Kernel I/O subsystem
- Functionality that is general and independent of any specific I/O device

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User-Level Software

- User-level buffering
 - e.g., stdio
- Spooling daemons
 - printer
 - network

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I/O Layering

- I/O Layers
 - User processes
 - Device-independent software
 - Device drivers
 - Device Controllers
 - Devices (HW)



I/O Devices

- Block device
 - accesses information in addressable fixed size blocks
 - example
 - disk

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I/O Devices

- Character device
 - accesses information in terms of streams of characters
 - examples
 - network, terminals, printers, mice

I/O Devices

- Other
 - memory-mapped
 - examples
 - graphics, video

I/O Devices

- Characteristics of I/O devices
 - character-stream or block
 - sequential or random-access
 - synchronous or asynchronous
 - sharable or dedicated
 - speed of operation
 - read-write, read only, or write only

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Device Controllers

- Interrupts
- Direct Memory Access (DMA)

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Interrupts

- When an I/O device has finished the work
 - it causes an interrupt
 - by asserting a signal on a bus line that is has been assigned to
 - this signal is detected by the interrupt controller, which decides what to do

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Interrupts

- The interrupt controller
 - processes the interrupt immediately (if no other interrupts are pending)
 - to handle the interrupt, the controller
 - puts a number on the address lines
 - specifying which device wants attention
 - and asserts a signal that interrupts the CPU

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Interrupts

- The interrupt signal causes the CPU to stop what it is doing
 - the number on the address lines is used as an index into a table called interrupt vector to bring...
 - ... a new program counter, that gives the appropriate interrupt service procedure (interrupt handler)

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Interrupts

- The interrupt service procedure
 - handles the interrupt
 - acknowledges the interrupt by writing a certain value to one of the interrupt controller's I/O ports
 - the I/O device is now free to generate a new interrupt

Direct Memory Access (DMA)

- Programmed I/O
 - CPU moves data word-by-word between device and memory
 - if device is slow, can be inefficient

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Direct Memory Access (DMA)

- DMA
 - CPU sets up transfer of data between device and memory
 - CPU can do other work while transfer occurs
 - interrupt occurs when DMA transfer completes

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Example: DMA from Disk

- · Read from disk
 - first transfer to disk's controller buffer
 - Then DMA to memory

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Kernel I/O Subsystem

- Concepts
 - Device independence
 - Uniform naming
 - Synchronous and Asynchronous
 - blocking (S)
 - · interrupt-driven (A)
 - Shared and dedicated

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Kernel I/O Subsystem

- Supervises
 - The management of the name space for files and devices
 - Access control to files and devices
 - Operation control
 - $\bullet \ e.g., \ a \ modem \ cannot \ seek$
 - File system space allocation
 - Device allocation

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Kernel I/O Subsystem

- Also
 - Buffering, caching, spooling, and device reservation
 - I/O scheduling
 - Device status monitoring, error handling, and failure recovery
 - Device driver configuration and initialization

Disks

- Disk Interleaving
- · Disk Scheduling

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Disks

- Performance
 - Seek Time
 - Rotational latency
- Improve: access time and bandwidth
- Bandwidth = number of bytes transferred divided by total time between 1st and last request

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Disk Interleaving

- A sector is read and it must be transferred to memory
- Disk head may pass beginning of next sector by the time transfer is done
- To improve performance, interleave sectors
 - single interleaving
 - double interleaving

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Disk Scheduling

- I/O request
 - input or output?
 - disk address
 - memory address for transfer
 - number of bytes

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Disk Scheduling

- If device driver and controller available
 - serve immediately
- else
 - request is placed in a queue

Disk Scheduling

 Scheduling means choosing from the pending I/O requests, which is going to be the next

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Scheduling Algorithms

- FCFS (First Come First Served)
 - fair but not necessarily the fastest service
 - example:
 - 98-183-37-122-14-124-65-67
 - · head starts at 53, will move 640 cylinders
 - problem: big swing! 122 -> 14 -> 124

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Scheduling Algorithms

- SSTF (Shortest Seek Time First)
 - can cause starvation
 - knowing the future would be better
 - not optimum
 - example:
 - 98-183-37-122-14-124-65-67
 - · head starts at 53, will move 236 cylinders

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Scheduling Algorithms

- SCAN
 - elevator algorithm
 - moves all the way back and forth
 - example:
 - 98-183-37-122-14-124-65-67
 - · head starts at 53, going downwards
 - · head will move 236

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Scheduling Algorithms

- · C-SCAN (Circular SCAN)
 - elevator algorithm
 - moves all the way back and forth
 - serves in one direction only
 - example:
 - 98-183-37-122-14-124-65-67
 - · head starts at 53 going upwards
 - · head will move 183 cylinders

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Scheduling Algorithms

- LOOK
 - elevator algorithm
 - moves back and forth
 - serves in both directions
 - example for LOOK:
 - 98-183-37-122-14-124-65-67
 - · head starts at 53 going upwards

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Scheduling Algorithms

- C-LOOK
 - elevator algorithm
 - moves back and forth
 - Serves in one direction only
 - example for C-LOOK:
 - 98-183-37-122-14-124-65-67
 - · head starts at 53 going upwards

· head will move 153 cylinders

Scheduling Algorithms

 Optimal will vary according to sequence of requests, but costs to determine optimal does not compensate for not using either SSTF or (C-)SCAN or (C-)LOOK

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Scheduling Algorithms

- File system organization will influence the requests for disk service
 - reading a contiguous file: requests are close together
 - reading a linked or indexed file: requests may be scattered

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Disk Scheduling

- Disk scheduling in modern systems can be implemented by the controller
- This is good for performance because disk has control over seek and rotational speed

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Disk Scheduling

- However, it is interesting for the OS to have control because of
 - priorities
 - \cdot demand paging over application I/O
 - writes over reads
 - I/O ordering
 - updating FS tables before starting writing a new file

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Performance

- Put directory info in the middle of the disk
- Cache directories and index blocks
- Best algorithm depends on FS implementation
- Good defaults
 - SSTF or (C-)LOOK or (C-)SCAN