# Constraint Satisfaction Problems

### CSEN 266 Artificial Intelligence

# Map Coloring Problem

- Look at the map of Australia
- Seven regions:
- Task: assign each region a color
  - Red, green, or blue
  - No neighboring regions have the same color



# What is a CSP?

- Formulate the problem as a CSP
  - **Variables:** the regions  $X = \{WA, NT, Q, NSW, V, SA, T\}$
  - The **domain** of each variable is the set  $D_i$  = {red, green, blue}
  - **Constraints:** neighboring regions have distinct colors 9 places where regions boarder: 9 constraints

C={SA $\neq$ WA, SA  $\neq$ NT, SA  $\neq$ Q,  $SA \neq NSW$ ,  $SA \neq V$ ,  $WA \neq NT$ ,  $NT \neq Q, Q \neq NSW, NSW \neq V$ 



# Defining a CSP

- Three components
  - X: a set of variables  $\{X_1, X_2, \dots, X_n\}$
  - D: a set of domains  $\{D_1, D_2, \dots, D_n\}$ , one for each variable
    - Each domain  $D_i$ : a set of allowable values,  $\{v_1, \dots, v_k\}$  for variable  $X_i$
  - C: a set of constraints that specify allowable combination of values for the variables

#### The Goal of a CSP

• Find an assignment of the values for the variables, such that the constraints are not violated.

### Example: N-Queens

- Variables: X<sub>ij</sub>
- Domains: {0, 1}
- Constraints:



$$\begin{aligned} \forall i, j, k \ (X_{ij}, X_{ik}) &\in \{(0, 0), (0, 1), (1, 0)\} \\ \forall i, j, k \ (X_{ij}, X_{kj}) &\in \{(0, 0), (0, 1), (1, 0)\} \\ \forall i, j, k \ (X_{ij}, X_{i+k,j+k}) &\in \{(0, 0), (0, 1), (1, 0)\} \\ \forall i, j, k \ (X_{ij}, X_{i+k,j-k}) &\in \{(0, 0), (0, 1), (1, 0)\} \end{aligned}$$

$$\sum_{i,j} X_{ij} = N$$

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#### Example: Sudoku



- Variables:
  - Each (open) square
- Domains:
  - {1,2,...,9}
- Constraints:

9-way alldiff for each column

9-way alldiff for each row

9-way alldiff for each region

#### Solve a CSP as a Search Problem

- State Space
  - Each state: an assignment of values to some or all of the variables  $\{X_i = v_i, X_j = v_j, \cdots\}$ 
    - Consistent assignment: does not violate any constraints
    - Complete assignment: every variable is assigned a value
    - Partial assignment: only some of the variables have been assigned values



#### Solve a CSP as a Search Problem

- Actions
  - An action is to assign a value to an un-assigned variable



### Solve a CSP as a Search Problem

- A Goal State of a CSP
  - A complete & consistent assignment
  - Such as

{WA=**red**, NT=**green**, Q=**red**, NSW=**green**, V=**red**, SA=**blue**, T=**green**}

- Goal Test
  - To check whether the current assignment is consistent and complete



### **Constraint Graph**

- Nodes: variables
- Arcs (Links): constraints
  - An arc connects two variables that participate in a constraint





# Variations of CSPs

- Unary constraints
  - Restrict the value of a single variable
  - Example: SA≠ Green
- **Binary** constraints
  - Constraints between two variables
  - − Example: SA  $\neq$  WA
  - A **Binary CSP**:
    - Only has binary constraints



# Variations of CSPs

- Higher-order constraints
  - involve 3 or more variables
  - Example: SA ≠ WA ≠ NT, i.e. Alldiff(SA,WA,NT)
- Global constraints (a general case)
  - Involve an arbitrary number of variables
  - Need not involve all variables
  - Example: Alldiff
    - All of the variables involved in the constraint must have different values



### **Cryptarithmetic Puzzles**

- Each letter represents a distinct digit (0-9)
  - Global constraint: square box at the top Alldiff(F,T,U,W,R,O)
  - Four column constraints

$$O + O = R + 10 \cdot C_1$$
  

$$C_1 + W + W = U + 10 \cdot C_2$$
  

$$C_2 + T + T = O + 10 \cdot C_3$$
  

$$C_3 = F$$





#### **Constraint Propagation**

- Arc consistency: a variable in a CSP is arc-consistent if
  - Every value in its domain satisfies the variable's binary constraints with other variables
  - Formal definition:
  - Variable  $X_i$  is arc-consistent with respect to (w.r.t.) another variable  $X_j$  if for every value in the current domain  $D_i$ , there is some value in the domain  $D_j$  that satisfies the binary constraint on the arc( $X_i, X_j$ ).

#### **Constraint Propagation**

- A network is **arc-consistent** if
  - Every variable is arc-consistent with every other variable
- Example



Domain of X and Y: digits (0 to 9) Constraint:  $Y = X^2$ 

• How to check the arc-consistency of this network?

# **Constraint Propagation**

- $D(X) = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$
- D(Y) = {0,1,2,3,4,5,6,7,8,9}
- Constraint:  $Y = X^2$
- Need to check two arcs: (X,Y) and (Y,X)
- Check (X,Y)
  - Update: D(X) = {0,1,2,3}
  - Check (Y,X)
    - Update: D(Y) = {0,1,4,9}

# AC-3 Algorithm

- The most popular algorithm that makes every variable arc-consistent in a CSP
- Maintains a queue (indeed, a set) of arcs to consider
- Step 1: Initially
  - The queue contains all arcs in the CSP
    - Each binary constraint becomes 2 arcs, one in each direction
    - e.g. arc  $(X_i, X_j)$  means arc  $X_i \rightarrow X_j$ arc  $(X_j, X_i)$  means arc  $X_j \rightarrow X_i$

# AC-3 Algorithm

- Step 2: Check the arcs in the queue one by one, until the queue is empty
  - Pops off an  $\operatorname{arc}(X_i, X_j)$  from the queue
  - Makes  $X_i$  arc-consistent with respect to  $X_i$ 
    - If D<sub>i</sub> is changed when we check the arc consistency of (X<sub>i</sub>, X<sub>j</sub>): add to the queue all arcs (X<sub>k</sub>, X<sub>i</sub>) where X<sub>k</sub> is a neighbor of X<sub>i</sub>; k ≠ j

i.e. add to the queue the incoming arcs to  $X_i$  except  $(X_i, X_i)$ 

• If  $D_i$  is revised down to nothing: Returns failure



- AC-3 reduces the domains of variables
  - State space is smaller for the search algorithm

- Consider the following binary constraint network:
  - 4 variables: X1, X2, X3, X4
  - Domains:
    - D1 = {1,2,3,4}
    - D2= {3,4,5,8,9}
    - D3 = {2,3,5,6,7,9}
    - D4= {3,5,7,8,9}
  - Constraints:
    - X1≥X2
    - X2>X3 or X3-X2=2
    - X3≠X4

• a). Draw the constraint graph

4 variables: X1, X2, X3, X4 => <u>4 nodes</u>



- a). Draw the constraint graph
- 4 variables: X1, X2, X3, X4 => <u>4 nodes</u>

Constraints:

- X1 >=X2
- X2 > X3 or
- (X3 X2) = 2
- X3 <> X4



- b). Is the network arc consistent? If not, compute the arc-consistent network using the AC-3 algorithm
- Arc X→Y is consistent iff for every value x of X there is some allowed y of Y
  - X1=1<D2={3,4,5,8,9}</pre>
  - Not arc consistent!



Domains:

- Run AC-3 Algorithm
- Queue of arcs:

(X1, X2), (X3,X2), (X2,X3), (X4, X3), (X2,X1), (X3,X4)

- Current Domain
- D1={1,2,3,4}
- D2={3,4,5,8,9}
- D3={2,3,5,6,7,9}
- D4={3,5,7,8,9}



- Run AC-3 Algorithm
- Queue of arcs: (X1,X2), (X3,X2), (X2,X3), (X4, X3), (X2,X1), (X3,X4)
- Check (X1,X2)
  - Constraint: X1>=X2
- Current Domain
- D1={1,2,3,4}
- D2={3,4,5,8,9}
- D3={2,3,5,6,7,9}
- D4={3,5,7,8,9}
- Result: Remove {1,2} from D1



- Run AC-3 Algorithm
- Queue of arcs: (X1,X2), (X3,X2), (X2,X3), (X4, X3), (X2,X1), (X3,X4)neighbor of  $X_i, k \neq j$  (i.e. incoming arcs to  $X_i$  except that from  $X_j$ ) (X1,X2), (X3,X2), (X2,X3), (X4, X3), (X2,X1), (X3,X4)
- Check (X1,X2)
  - Constraint: X1>=X2
- Current Domain
- D1={3,4}
- D2={3,4,5,8,9}
- D3={2,3,5,6,7,9}
- D4={3,5,7,8,9}
- Result: Remove {1,2} from D1



If  $D_i$  is changed while checking arc

consistency of  $(X_i, X_j)$ : add to the

queue all arcs  $(X_k, X_i)$  where  $X_k$  is a

Recall: AC-3

- Run AC-3 Algorithm
- Queue of arcs:

(X3,X2), (X2,X3), (X4, X3), (X2,X1), (X3,X4)

- Check (X3,X2)
  - Constraints: X2>X3 or (X3-X2)=2
- Current Domain
- D1={3,4}
- D2={3,4,5,8,9}
- D3={2,3,5,6,7,9}
- D4={3,5,7,8,9}
- Result: Remove {9} from D3



- Run AC-3 Algorithm
- Queue of arcs: arcs to X
   (X3,X2), (X2,X3), (X4, X3), (X2,X1), (X3,X4)

Recall: AC-3

If  $D_i$  is changed while checking arc consistency of  $(X_i, X_j)$  : add to the queue all arcs  $(X_k, X_i)$  where  $X_k$  is a neighbor of  $X_i$ ,  $k \neq j$  (i.e. incoming arcs to  $X_i$  except that from  $X_j$ )

• Check (X3,X2)

Constraints: X2>X3 or (X3-X2)=2

- Current Domain
- D1={3,4}
- D2={3,4,5,8,9}
- D3={2,3,5,6,7}
- D4={3,5,7,8,9}
- Result: Remove {9} from D3



- Run AC-3 Algorithm
- Queue of arcs:

(X2,X3), (X4, X3), (X2,X1), (X3,X4)

- Check (X2,X3)
  - Constraints: X2>X3 or (X3-X2)=2
- Current Domain
- D1={3,4}
- D2={3,4,5,8,9}
- D3={2,3,5,6,7}
- D4={3,5,7,8,9}
- Result: do nothing



- Run AC-3 Algorithm
- Queue of arcs: (X4,X3), (X2,X1), (X3,X4)
- Check (X4,X3)
  - Constraints: X3<>X4
- Current Domain
- D1={3,4}
- D2={3,4,5,8,9}
- D3={2,3,5,6,7}
- D4={3,5,7,8,9}
- Result: do nothing



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- Run AC-3 Algorithm
- Queue of arcs: (X2,X1), (X3,X4)
- Check (X2,X1)
  - Constraints: X1>=X2
- Current Domain
- D1={3,4}
- D2={3,4,5,8,9}
- D3={2,3,5,6,7}
- D4={3,5,7,8,9}
- Result: Remove {5,8,9} from D2



- Run AC-3 Algorithm
- Queue of arcs: (X2,X1), (X3,X4)
- Check (X2,X1)

   Constraints: X1>=X2
- Current Domain
- D1={3,4}
- D2={3,4}
- D3={2,3,5,6,7}
- D4={3,5,7,8,9}
- Result: Remove {5,8,9} from D2

#### Recall: AC-3

If  $D_i$  is changed while checking arc consistency of  $(X_i, X_j)$  : add to the queue all arcs  $(X_k, X_i)$  where  $X_k$  is a neighbor of  $X_i$ ,  $k \neq j$  (i.e. incoming arcs to  $X_i$  except that from  $X_j$ )



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- Run AC-3 Algorithm
- Queue of arcs: (X2,X1), (X3,X4), (X3,X2)
- Check (X2,X1)

   Constraints: X1>=X2
- Current Domain
- D1={3,4}
- D2={3,4}
- D3={2,3,5,6,7}
- D4={3,5,7,8,9}
- Result: Remove {5,8,9} from D2,
- add (X3,X2) to queue

#### Recall: AC-3

If  $D_i$  is changed while checking arc consistency of  $(X_i, X_j)$  : add to the queue all arcs  $(X_k, X_i)$  where  $X_k$  is a neighbor of  $X_i$ ,  $k \neq j$  (i.e. incoming arcs to  $X_i$  except that from  $X_j$ )



- Run AC-3 Algorithm
- Queue of arcs: (X3,X4), (X3,X2)
- Check (X3,X4)
   Constraints: X3<>X4
- Current Domain
- D1={3,4}
- D2={3,4}
- D3={2,3,5,6,7}
- D4={3,5,7,8,9}
- Result: do nothing



- Run AC-3 Algorithm
- Queue of arcs: (X3,X2)
- Check (X3,X2)
  - Constraints: X2>X3 or (X3-X2)=2
- Current Domain
- D1={3,4}
- D2={3,4}
- D3={2,3,5,6,7}
- D4={3,5,7,8,9}
- Result: remove {7} from D3



- Run AC-3 Algorithm
- Queue of arcs: (X3,X2)

Recall: AC-3

If  $D_i$  is changed while checking arc consistency of  $(X_i, X_j)$  : add to the queue all arcs  $(X_k, X_i)$  where  $X_k$  is a neighbor of  $X_i$ ,  $k \neq j$  (i.e. incoming arcs to  $X_i$  except that from  $X_j$ )

- Check (X3,X2)
  - Constraints: X2>X3 or (X3-X2)=2
- Current Domain
- D1={3,4}
- D2={3,4}
- D3={2,3,5,6}
- D4={3,5,7,8,9}
- Result: remove {7} from D3



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- Run AC-3 Algorithm
- Queue of arcs: (X3,X2), (X4,X3)
- Check (X3,X2)
  - Constraints: X2>X3 or (X3-X2)=2
- Current Domain
- D1={3,4}
- D2={3,4}
- D3={2,3,5,6}
- D4={3,5,7,8,9}
- Result: remove {7} from D3,
- add (X4,X3) to queue



- Run AC-3 Algorithm
- Queue of arcs: (X4,X3)
- Check (X4,X3)
  - Constraints: X3<>X4
- Current Domain
- D1={3,4}
- D2={3,4}
- D3={2,3,5,6}
- D4={3,5,7,8,9}
- Result: do nothing



- Run AC-3 Algorithm
- Queue of arcs:

None

- Reduced Domain (Arc Consistent)
- D1={3,4}
- D2={3,4}
- D3={2,3,5,6}
- D4={3,5,7,8,9}



- C. Is the network arc consistent? If yes, give a solution.
  - 4 variables: X1, X2, X3, X4
  - Constraints:
    - X1 >=X2
    - X2 > X3 or (X3 − X2) = 2
    - X3 <> X4
  - Network is arc-consistent for domains:
    - D1' = {3, 4}
    - D2' = {3, 4}
    - D3' = {2, 3, 5, 6}
    - D4' = {3, 5, 7, 8, 9}
  - One of possible solutions is:

X1 = 3; X2 = 3; X3 = 2; X4 = 3

#### **Backtracking Search**



# Variable Ordering

- Which variable should be assigned next?
  - SELECT-UNASSIGNED-VARIABLE
- Static Ordering
  - Chooses the next unassigned variable in order,  $\{X_1, X_2, ...\}$
  - Seldom results in the most efficient search

#### **MRV** heuristic

- Minimum-Remaining-Values (MRV) heuristic: Chooses the variable with the fewest "legal" values
  - Example:
    - WA=red, NT=green, then
    - Only one possible value for SA, SA=blue
    - (rather than assigning Q next)
  - Also called
    - The "most constrained variable"
  - Usually performs better than a random or static ordering



#### **Degree Heuristic**

- The MRV heuristic doesn't help at all in choosing the first region to color in Australia
- Degree heuristic: selects the variable that is involved in the largest number of constraints
  - Example: SA has the highest degree, 5; other variables have degree 2 or 3 (exception: T has 0)



# Value Ordering

- Once a variable has been selected, in what order should its values be tried?
- The **least-constraining-value** heuristic:
  - prefers the value that rules out the fewest choices for the neighboring variables in the constraint graph



#### Value Ordering

- least-constraining-value heuristic:
- Example: WA=red, NT=green, and our next choice is for Q
  - Q=blue: bad choice, eliminates the last legal value left for Q's neighbor SA.
  - The least-constraining-value heuristic:
    - Prefers Q=red Tries to leave the
    - maximum flexibility for subsequent variable assignments
- Rule of thumb: fail-last



# **Forward Checking**

- When solving a CSP, we can apply inference methods
- Purpose: infer reductions of the domain for other variables
- Forward Checking
  - Keep track of remaining legal values for unassigned variables that are connected to current variable.
  - Terminate search (Backtrack) when any variable has no legal values

#### **Forward Checking**







 a. Forward checking: NT has been assigned a value as shown. Cross out all values that would be eliminated by Forward Checking.



VVA		Q	<b>5</b> A	INDAN	V	
RGB	G	RGB	RGB	RGB	RGB	RGB

• Answer:

WA	NT	Q	SA	NSW	V	Т
R 🗙 B	G	R	RB	RGB	RGB	RGB

 b. Minimum-remaining-value (MRV) heuristic: consider the assignment below. WA is assigned and forward checking has been done. List all unassigned variables that might be selected by the MRV heuristic



#### • Answer:

• NT, SA

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 c. Degree heuristic: consider the assignment below. WA is assigned and forward checking has been done. List all unassigned variables that might be selected by the Degree heuristic



#### • Answer:

• SA

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# Local Search for CSP

- Use a complete-state formulation
  - the initial state has assigned a value to every variable
  - The search changes the value of one variable at a time
- Example: the 8-queens problem
  - the initial state might be a random configuration of 8 queens in 8 columns
    - the initial assignment violates several constraints
  - each step moves a single queen to a new position in its column
- The point of local search: to eliminate the violated constraints

# Local Search for CSP

- The min-conflicts heuristic
  - In choosing a new value for a variable, select the value that results in the minimum number of conflicts with other variables

# **Min-Conflicts Heuristic**

• Example



**Figure 6.9** A two-step solution using min-conflicts for an 8-queens problem. At each stage, a queen is chosen for reassignment in its column. The number of conflicts (in this case, the number of attacking queens) is shown in each square. The algorithm moves the queen to the min-conflicts square, breaking ties randomly.

You are given the following constraint graph representing a map that has to be colored with three colors, red (R), green (G) and blue (B), subject to the constraints that no adjacent regions, which are connected by an arc in the graph, are assigned the same color.



Consider the set of inconsistent assignments below. Variable **C** has just been selected to be assigned a new value during a local search for a complete and consistent assignment. What new *value* will be selected for variable **C** by the **Min-Conflicts Heuristic**?

Α	В	С	D	E	F
В	G		G	G	В

Answer: R